

Review for heat equation.

Physical meaning.

(Assume $x \in \Omega$, $\partial\Omega$ is $C^1 \dots$)

Consider $U(t, x)$, which represents something like energy at space x , time t .
And here, we can take $\int_{\Omega} U(t, x) dx$ as the whole energy.

$\Rightarrow \frac{d}{dt} \int_{\Omega} U(t, x) dx$ is the change of energy w.r.t time.

And let $J(t, x)$ be the energy flux.

$$\Rightarrow \frac{d}{dt} \int_{\Omega} U(t, x) dx = - \int_{\partial\Omega} J(t, x) \cdot n \, dS = - \int_{\partial\Omega} \nabla U \, dx$$

Sometimes $J(x, t) = -k \nabla U(t, x)$, $\Rightarrow$

Three kind of boundary condition

① $U|_{\partial\Omega} = N$ (Dirichlet)

② $\frac{\partial U}{\partial n}|_{\partial\Omega} = N$ (Neumann)

③ $-k \frac{\partial U}{\partial n}|_{\partial\Omega} = H(U - N)|_{\partial\Omega}$ (Mixed)

(Here, assume $U_t = \alpha^2 \Delta U$

's $\alpha \neq 1$, otherwise, $v(t, x) = U(t, \alpha x)$).

I) Classical solution is unique:

classical.

$$\begin{cases} U_t = \Delta U + f \\ U(0, x) = \varphi(x) \\ U|_{\partial\Omega} = \text{bdry condition.} \end{cases}$$

$$\Leftrightarrow \begin{cases} U_t = \Delta U \\ U(0, x) = 0 \\ U|_{\partial\Omega} = \text{homogeneous bdy condition} \end{cases}$$

only has ∇ solution 0

Proof: Consider $e(t) = \frac{1}{2} \int_{\Omega} U^2(t, x) dx$, $e(0) = 0$

$$\Rightarrow e(t) = \int_{\Omega} U(t, x) U_t(t, x) dx$$

$$= \int_{\Omega} U(t, x) \Delta U \, dx$$

$$= \int_{\partial\Omega} U \frac{\partial U}{\partial n} \, dS - \int_{\Omega} |\nabla U(t, x)|^2 dx$$

≤ 0

II. To give a way to deduce a solution, on $\mathbb{R}^d$.

It's natural to review some Fourier transform.

- $(f * g)^\wedge = \hat{f} \hat{g}$
- $\int \hat{f} \hat{g} = \int f \bar{g}$ } First holds for $L^1(\mathbb{R}^d)$, other condition need some additional knowledge.
- If $f, \hat{f} \in L^1 \Rightarrow f = (\hat{\hat{f}})^\vee$ (inversion formula).

• For $f \in C_c^\infty(\mathbb{R}^d)$, $(D^\alpha f)^\wedge = (2\pi i)^\alpha \xi^\alpha \hat{f}$
(Just integration by parts)

$$\text{Now. } \begin{cases} U_t = \Delta U \\ U(0, x) = \varphi(x) \end{cases} \Rightarrow \begin{cases} \hat{U}_t = -4\pi^2 \xi^2 \hat{U} \\ \hat{U}(0, \xi) = \hat{\varphi}(\xi) \end{cases}$$

$$\Rightarrow \hat{U}(\xi) = e^{-4\pi^2 \xi^2 t} \hat{\varphi}(\xi)$$

$$\text{So } (?)^\wedge = e^{-4\pi^2 \xi^2 t}$$

By residue formula, one can show that in $\mathbb{R}^d$

$$\left(\frac{1}{\sqrt{4\pi t}} e^{-\frac{x^2}{4t}} \right)^\wedge = e^{-4\pi^2 \xi^2 t}$$

Set $G_t(x) = \frac{1}{\sqrt{4\pi t}} e^{-\frac{x^2}{4t}}$ $\Rightarrow U(t, x) = G_t(x) * \varphi(x)$ ↗ supposed to be

(Thm): Consider on $\mathbb{R}^d$.

$$\begin{cases} U_t = \Delta U, t > 0, x \in \mathbb{R}^d \\ U(0, x) = \varphi(x), \end{cases} \quad \varphi \in C(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d)$$

① $U(t, x) = G_t * \varphi \in C^\infty((0, \infty) \times \mathbb{R}^d)$, $U_t = \Delta U$

② $\lim_{t \rightarrow 0, x \rightarrow x_0} U(t, x) = \varphi(x_0)$, $x_0 \in \mathbb{R}^d$.

Pf: Lemma: $f, g \in L^1(\mathbb{R}^d)$, $\partial_{x_i} f \in C(\mathbb{R}^d) \cap L^1(\mathbb{R}^d) \cap L^\infty(\mathbb{R}^d)$,

Then $\partial_{x_i}(g * f) = g * \partial_{x_i} f$.

Lemma's pf: Consider $\frac{1}{h} \int (f(x-y+he_i) - f(x-y)) g(y) dy$

From DCT: $h \rightarrow 0$, dominated by $2 \|\partial_{x_i} f\|_{L^\infty} g(y) \dots \Rightarrow \square$

So by this, we can just transform U_t, U_{x_i} to G_t, G_{x_i} :
 $\partial_t(G * \varphi) = G * \varphi, \dots \Rightarrow C^\infty$ and satisfies ①.

For the initial condition, consider (Approximation identity).

Lemma $k_n(x)$ non-negative cts, s.t

$$\textcircled{1} \int_{\mathbb{R}^d} k_n(x) dx = 1 \quad \textcircled{2} \forall \varepsilon > 0, \lim_{n \rightarrow \infty} \int_{|x| \geq \varepsilon} k_n(x) dx = 0.$$

Then $\forall g(x)$ is continuous ^{near 0} and bdd.

$$\lim_{n \rightarrow \infty} \int_{\mathbb{R}^d} k_n(x) g(x) dx = g(0) = \int g(x) \delta(x) dx$$

Lemma's pf: consider $\left| \int_{\mathbb{R}^d} k_n(x) (g(x) - g(0)) dx \right|$

$$\leq \int_{|x| \leq \varepsilon} |k_n(x)| |g(x) - g(0)| + \int_{|x| \geq \varepsilon} k_n(x) |g(x) - g(0)| \dots$$

Leverage g is cts

Leverage g is bdd.

From the Lemma, as $t \rightarrow 0$, we can take $G_t(x)$ as an approximation identity.

On $\mathbb{R}^d$, there exists non-homogeneous condition

$$\begin{cases} U_t = \Delta U + f \\ U|_{t=0} = 0. \end{cases} \quad \textcircled{A}$$

Duhamel principle Let $f \in C^{1,2}([0,\infty) \times \mathbb{R}^d) \cap C_c([0,\infty) \times \mathbb{R}^d)$

$$U(t,x) = \int_0^t \int_{\mathbb{R}^d} G_{t-s}(x-y) f(s,y) dy ds \text{ solves } \textcircled{A}$$

(初值条件 $\bar{u}_0, \bar{u}_1$).

III) On bounded domain, the story is different.

Before introducing further, let's consider the Sturm-Liouville boundary problem:

$$\begin{cases} -\Delta u = \lambda u, \quad u \end{cases}$$

$$\begin{cases} \alpha u + \beta \frac{\partial u}{\partial n} = 0, \quad \partial \Omega, \quad \alpha, \beta \geq 0, \quad \alpha + \beta > 0 \end{cases} \Rightarrow (\lambda, u) \text{ is called an eigenpair.}$$

(Here, α, β can be changed to $\alpha(x), x \in \Omega$ and $\beta(x), x \in \partial \Omega$)

We have:

① If $(\lambda_1, u_1), (\lambda_2, v_1)$ are eigenpairs, then we have:

$$\begin{aligned} \int_{\Omega} -\Delta u_1 v_1 dx &= - \int_{\partial \Omega} \frac{\partial u_1}{\partial n} v_1 dS + \int_{\Omega} \nabla u_1 \cdot \nabla v_1 dx \\ &= - \int_{\partial \Omega} \frac{\partial v_1}{\partial n} u_1 dS + \int_{\Omega} \nabla u_1 \cdot \nabla v_1 dx = \int_{\Omega} -\Delta v_1 u_1 dx \\ \begin{pmatrix} u_1 & \frac{\partial u_1}{\partial n} \\ v_1 & \frac{\partial v_1}{\partial n} \end{pmatrix} \begin{pmatrix} \alpha \\ \beta \end{pmatrix} &= 0 \Rightarrow u_1 \frac{\partial v_1}{\partial n} - \frac{\partial u_1}{\partial n} v_1 = 0 \end{aligned}$$

② Each eigenvalue of Δ is real

③ Eigenvalues are countable, $0 \leq \lambda_1 \leq \lambda_2 \leq \lambda_3 < \dots$, $\lim_{n \rightarrow \infty} \lambda_n = \infty$

④ $\lambda_1 \neq \lambda_2$ are eigenvalues. $\lambda_1 \leftrightarrow u_1, \lambda_2 \leftrightarrow u_2 \Rightarrow \int_{\Omega} u_1 u_2 = 0$, i.e. they

are orthogonal in $L^2(\Omega)$

In fact, the eigenfunction forms an orthogonal basis for $L^2(\Omega)$.

We only prove why eigenvalue $\lambda \geq 0$ and the orthogonality.

(i) Assume that (λ, u) is an eigenpair.

$$\begin{aligned}\lambda \int_{\Omega} u^2 dx &= \int_{\Omega} -\Delta u u dx \\ &= -\int_{\partial\Omega} \frac{\partial u}{\partial n} u dS + \int_{\Omega} |\nabla u|^2 dx \geq 0\end{aligned}$$

(ii) $(\lambda, u), (\eta, v)$ is an eigenpair.

$$\begin{aligned}\text{Then, we have: } \lambda \int_{\Omega} uv dx &= \int_{\Omega} -\Delta u v dx \\ &= -\int_{\partial\Omega} \frac{\partial u}{\partial n} v dS + \int_{\Omega} \nabla u \cdot \nabla v \\ &= -\int_{\partial\Omega} \frac{\partial v}{\partial n} u dS + \int_{\Omega} \nabla v \cdot \nabla u = \eta \int_{\Omega} uv dx \Rightarrow \square\end{aligned}$$

Now, we propose a method to solve HE in 1 dimension.

$$\begin{cases} u_t = \Delta u + f \\ u(t, x) = \varphi(x) & \text{for } x \in (0, 1) \\ \alpha_1 u_x(0) + \beta_1 u(0) = g_1(t) \\ \alpha_2 u_x(1) + \beta_2 u(1) = g_2(t) \end{cases}$$

Naturally, we always focus $\begin{cases} u(t, 0) = g_1(t) \\ u(t, 1) = g_2(t) \end{cases}$ or $\begin{cases} u'(t, 0) = g_1(t) \\ u'(t, 1) = g_2(t) \end{cases}$ or mixed.

$$\text{Use } \tilde{u}(t, x) = u(t, x) - \frac{x}{1} g_1(t) \begin{cases} -\frac{x}{1} g_2(t) \\ +\frac{(x-1)}{2!} g_2(t) \end{cases} \Rightarrow \text{deal. respectively}$$

So, we just need to deal with $g_1(t) \equiv g_2(t) \equiv 0$

Consider $X_n(x) T_n(t)$ which satisfies $\begin{cases} U_t = \Delta U \\ \alpha_1 U(x, 0) + \beta_1 U(0) = 0 \\ \alpha_2 U(x, 1) + \beta_2 U(1) = 0 \end{cases}$

$$\text{Then } \begin{cases} X_n(x) T_n'(t) = X_n''(x) T_n(t) \Rightarrow \frac{X_n''(x)}{X_n(x)} = \frac{T_n'(t)}{T_n(t)} = -\lambda_n \\ \alpha_1 X_n'(0) + \beta_1 X_n(0) = 0 \\ \alpha_2 X_n'(1) + \beta_2 X_n(1) = 0 \end{cases}$$

From above, we have $\lambda_n \geq 0$ and for all eigenvalues λ , the eigenfunctions $\{X_n(x)\}$ forms a orthogonal basis in $L^2(0, 1)$

Hence, if $\varphi(x) \in L^2(0, 1) \Rightarrow$ we can decompose $\varphi(x) = \sum_{n=1}^{\infty} \varphi_n X_n(x)$
 $(\varphi_n = \frac{\int_0^1 \varphi(x) X_n(x) dx}{\int_0^1 X_n^2(x) dx})$.

if $f(x) \in L^2(0, 1) \Rightarrow$ We can decompose $f(x) = \sum_{n=1}^{\infty} f_n X_n(x)$

Back to the original situation.

We just need to let $\begin{cases} T_n'(t) = -\lambda T_n(t) + f_n(t) \\ T_n(0) = \varphi_n \end{cases}$, then $\sum_{n=1}^{\infty} T_n(t) X_n(x)$ solves the HE.

IV). Maximum principle and related energy estimate. Comparison principle.

Maximum principle (HE version, and we will state a generalized version here). $\Delta U = f$ For U is bounded and open
 If $U \in C^{1,2}([0, T] \times \bar{U}) \cap C(\bar{U}_T)$ and consider the operator:

$$L_u = \sum_{i,j=1}^n a_{ij}(t,x) \partial_i \partial_j u, \text{ where } A = (a_{ij}(t,x)) \text{ is positive semidefinite}$$

$\nearrow \dim U$ $\nearrow \partial_i \partial_j \sum_{i=1}^n b_i(t,x) \partial_i u$

If $u_t - Lu \leq 0$, then $\max_{\bar{U}_T} u = \max_{\partial U_T} u$

Proof: First, assume $u_t - Lu < 0$.

If there exists $(t_0, x_0) \in [0, T] \times U$, s.t. $u(t_0, x_0) = \max_{\bar{U}_T} u$
 $\Rightarrow \begin{cases} u_t \geq 0, \nabla^2 u(t_0, x_0) \leq 0 \Rightarrow A \nabla^2 u(t_0, x_0) \leq 0 \\ \partial_i u = 0 \end{cases} \Rightarrow Lu \leq 0$

$\Rightarrow u_t - Lu \geq 0 \Rightarrow \text{Contradiction.}$

If $u_t - Lu \leq 0$, consider $U_\varepsilon(t, x) = u - \varepsilon t \geq u$, let $\varepsilon \rightarrow 0^+$ is enough.

As a particular example, we have: if $u_t - Lu \leq 0$ for $u \in C^{1,2} \cap C^-$.
 Then $\max_{\bar{U}_T} u = \max_{\partial U_T} u$

From this, we can get the comparison principle
 For $u, v \in C^{1,2}(\bar{U}_T) \cap C(\bar{U}_T)$, if

$$\begin{cases} u_t - Lu \leq v_t - Lv \\ u|_{\partial U_T} \leq v|_{\partial U_T} \end{cases} \Rightarrow u \leq v \text{ in } \bar{U}_T.$$

Using this, we can give another proof of the uniqueness of heat equation.

Using this, it's easy to get:

L^∞ -stability: Let U_i be the classical solution $C^{1,2}(U_T) \cap C(\bar{U}_T)$, s.t. $\begin{cases} \partial_t U_i = \Delta U_i + f_i, & U_i \\ U_i|_{\partial U} = g_i, & U_i|_{t=0} = \varphi_i \end{cases}$

Then: $\max_{\bar{U}_T} |U_1 - U_2| \leq T \|f_1 - f_2\|_{L^\infty} + \|g_1 - g_2\|_{L^\infty} + \|\varphi_1 - \varphi_2\|_{L^\infty}$

Now, we propose L^∞ -stability for mixed boundary condition. Similarly, we need a comparison principle.

- $U \in C^{1,2}(U_T) \cap C^{0,1}(\bar{U}_T)$ satisfy $\begin{cases} LU = U_t - \Delta U \geq 0 \text{ in } U \\ U|_{t=0} \geq 0 \text{ in } U \\ \frac{\partial U}{\partial n} + \beta U|_{\partial U} \geq 0, t \in [0, T] \end{cases}$ $U = (0, 1)$
 $\beta: \partial U \rightarrow [0, \infty) \Rightarrow U \geq 0 \text{ in } \bar{U}_T$

Proof: Since $LU = U_t - \Delta U \geq 0$, we have $\min_{\bar{U}_T} U = \min_{\partial U_T} U$

If $\exists (t^*, x^*) \in \partial U_T$, s.t. $U(t^*, x^*) \leq 0$

Notice that $\nabla U(t^*, x^*) \cdot n \leq 0$, since (t^*, x^*) is minimal point.

So, $\frac{\partial U}{\partial n} + \beta U|_{\partial U} \leq 0$, if $\frac{\partial U}{\partial n} + \beta U|_{\partial U} > 0 \Rightarrow$ Contradiction

If not, consider $w(t, x) = 2t + (x - \frac{1}{2})^2$, $Lw = 0$, $w|_{t=0} \geq 0$ in U
 $\begin{cases} \frac{\partial w}{\partial n} + \beta w|_{\partial U} \geq c > 0. \end{cases}$

And, consider $U_\varepsilon = U + \varepsilon w \geq U$ as $\varepsilon \rightarrow 0^+$.

Hence, we get: If $U \in C^{1,2}(U_T) \cap C^{0,1}(\bar{U}_T)$, s.t.

$\begin{cases} LU = U_t - \Delta U = f(t, x) \\ U|_{t=0} = \Phi \\ \frac{\partial U}{\partial n} + \beta U|_{\partial U} = g(t, x) \end{cases} \Rightarrow \max_{\bar{U}_T} U \leq C(T+1) (\|f\|_{L^\infty} + \|\Phi\|_{L^\infty} + \|g\|_{L^\infty})$

Proof: Consider $F_t + \Phi + \frac{G}{C} w(t, x) \pm U(t, x)$

□

Here, we give an application of maximum principle to finish the discussion about HE.

For HE on the whole space, if $U \in C^{1,2}([0, T] \times \mathbb{R}^d) \cap C([0, T] \times \mathbb{R}^d)$ solves $\begin{cases} \partial_t U = \Delta U \\ U|_{t=0} = \varphi \end{cases}$ with $|U(t, x)| \leq Ae^{a|x|^2}$ for some $A > 0, a > 0$.

Then $\max_{[0, T] \times \mathbb{R}^d} |U| = \sup_{\mathbb{R}^d} |\varphi|$.

Proof: Notice that: $\frac{\nu}{(T+\varepsilon-t)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}}$ is a solution of $U_t = \Delta U$.

$$(U_t = -\frac{d}{2} \frac{\nu \cdot (-1)}{(T+\varepsilon-t)^{\frac{d}{2}+1}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}} + \frac{\nu}{(T+\varepsilon-t)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}} \frac{-|x|^2 \cdot (-1)}{4(T+\varepsilon-t)^2})$$

$$U_{x_i} = \frac{\nu}{(T+\varepsilon-t)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}} \cdot \frac{2x_i}{4(T+\varepsilon-t)} = \frac{\nu x_i}{2(T+\varepsilon-t)^{\frac{d}{2}+1}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}}$$

$$U_{x_i x_i} = \frac{\nu}{2(T+\varepsilon-t)^{\frac{d}{2}+1}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}} + \frac{\nu x_i^2}{4(T+\varepsilon-t)^{\frac{d}{2}+2}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}}$$

So, consider $V(t, x) = U(t, x) - \frac{\nu}{(T+\varepsilon-t)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon-t)}}$

Take $T+\varepsilon < \frac{1}{4a}$, take L big enough, consider $[0, T] \times B_L(0)$

Then, we have:

$$\partial_t V = \Delta V \Rightarrow \max_{[0, T] \times B_L(0)} V = \max_{\partial(\sim)} V$$

When $t=0$, $V(0, x) \leq \varphi(x)$ On $\partial B_L(0)$, $V(t, x) \leq Ae^{a|x|^2} - \frac{\nu}{(T+\varepsilon)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon)}}$

$$\leq Ae^{a|x|^2} - \frac{\nu}{(T+\varepsilon)^{\frac{d}{2}}} e^{\frac{|x|^2}{4(T+\varepsilon)}} \leq 0 \leq \sup_{\sim} \varphi$$

$$\Rightarrow \sup_{(0,T] \times B_{1/2}} v(t,x) \leq \sup_{\mathbb{R}^d} \varphi \quad \mu \rightarrow 0 \Rightarrow \sup_{(0,T] \times B_{1/2}} v(t,x) \leq \sup_{\mathbb{R}^d} \varphi.$$

Similarly, let $\tilde{v}(t,x) = -v(t,x) + \frac{\mu}{(T+\varepsilon-t)^2} e^{\frac{|x|^2}{4(T+\varepsilon-t)}}$ is minimum ...

$$\Rightarrow \min_{(0,T] \times B_{1/2}} \tilde{v} \geq \min_{\mathbb{R}^d} \varphi \Rightarrow \min_{\sim} v \geq \min_{\sim} \varphi \quad \text{or inf, just leverage bdd + closed} \Rightarrow \text{opt!}$$

Finally, we give the energy estimate

$$\text{Let } u \in C^{1,2}(U_T) \cap C(\bar{U}_T) \text{ solves } \begin{cases} (\partial_t - \Delta)u = f, & U_T \\ u|_{t=0} = \varphi \\ u|_{\partial U} = 0 \end{cases}$$

Then, $\exists C = C(T)$, s.t

$$\sup_{0 \leq t \leq T} \|u(t, \cdot)\|_{L^2(\omega)}^2 + 2 \int_0^T \|\nabla u(t, \cdot)\|_{L^2(\omega)}^2 dt \leq C (\|\varphi\|_{L^2(\omega)}^2 + \int_0^T \|f(t, \cdot)\|_{L^2(\omega)}^2 dt)$$

$$\text{Proof: } \int_{\omega} u(\partial_t - \Delta)u = \int_{\omega} u f, \text{ fix } t.$$

$$\text{Consider LHS} = \frac{1}{2} \frac{d}{dt} \int_{\omega} u^2(t,x) dx + \int_{\omega} |\nabla u(t,x)|^2 dx$$

$$\text{RHS} \leq \frac{1}{2} \int_{\omega} u^2 + f^2 dx$$

$$\text{Let } e(t) = \int_{\omega} u^2(t,x) dx, \text{ then } \dot{e}(t) \leq e(t) + 2 \int_{\omega} f^2 dx, e(0) = \int_{\omega} \varphi^2(x) dx$$

$$\Rightarrow (e^{-t} e(t))' \leq e^{-t} \cdot 2 \int_{\omega} f^2(t,x) dx \leq 2 \int_{\omega} f^2(t,x) dx$$

$$\Rightarrow e^{-t} e(t) - \int_{\omega} \varphi^2(x) dx \leq 2 \int_0^T \int_{\omega} f^2(t,x) dx dt$$

Using this, the energy estimate is obvious.

